

# Deformed microstructure in pressureless-sintered barium titanate

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## Abstract

The sintered microstructure of pressureless-sintered BaTiO<sub>3</sub> analysed by transmission electron microscopy (TEM) reveals that plastic deformation occurred at 1400 °C when the slip systems of  $\langle 1\bar{1}0 \rangle \{110\}$ ,  $\langle 100 \rangle \{110\}$  and  $\langle 100 \rangle \{001\}$  were activated by the intrinsic sintering stress ( $\Sigma$ ). Dislocations with the Burgers vectors  $\mathbf{b}_1 = \langle 110 \rangle$  and  $\mathbf{b}'_1 = \langle 100 \rangle$  have dissociated. The dissociation reactions of  $\mathbf{b}_1 = \mathbf{b}_2 + \mathbf{b}_3$  are:  $[101] \rightarrow [001] + [100]$  and  $[001] \rightarrow 1/2[101] + 1/2[1\bar{0}1]$ , respectively. Both dissociated dislocations contained a series of scallop-shaped half-loop partials with the Burgers vectors respectively of  $\mathbf{b}_3 = [100]$  and  $\mathbf{b}'_3 = 1/2[1\bar{0}1]$ . The dissociations took place by a climb mechanism. Polygonisation in dynamic recovery, necessitating both glide and climb of dislocations, occurred during sintering at 1400 °C, and which is clearly evidenced by sub-grain formation. Densification was contributed by dislocation mechanisms where the ceramic has been plastically deformed by the sintering stress. Densification of the undoped and Sr-doped BaTiO<sub>3</sub> compositions by pressureless-sintering in relation to the dislocation substructure is discussed.

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## 1. Introduction

BaTiO<sub>3</sub> perovskite is a ferroelectric ceramic used extensively in the electronic industries. Sintering of BaTiO<sub>3</sub> powder, made to a green body, is usually adopted to manufacture the passive components, e.g. dielectric capacitors. Dislocation mechanisms have long been suggested [1] to be an important contribution to the densification of ceramics. However, deformed microstructure in sintered ceramics has seldom been analysed in correlation to sintering at high temperatures.

It is also known [2–5] that the lower mantle of the earth being more silicic than the higher mantle is constituted predominantly of pyroxene (Mg,Fe)SiO<sub>3</sub> with the perovskite structure. The viscosity of the lower mantle may be investigated by looking into the plastic deformation of the perovskites [3] at high temperatures. Indeed, BaTiO<sub>3</sub> [7] and other perovskites [6–10] have been taken as model materials in understanding dislocation creep in the earth mantle.

All crystallographic indices here refer to the cubic structure, taking the tetragonal BaTiO<sub>3</sub> of  $\sim 1.01$  as pseudo-cubic [7]. Two types of dislocations with the Burgers vectors  $\mathbf{b}_1 = \langle 100 \rangle$  and  $\langle 110 \rangle$  were determined in the perovskites of KTaO<sub>3</sub> [4], KZnF<sub>3</sub> [6], CaTiO<sub>3</sub> [7], BaTiO<sub>3</sub> [7], SrTiO<sub>3</sub> [8,9] and CaGeO<sub>3</sub> [10], often taken as model materials to simulate deformation in the lower mantle. The  $\langle 1\bar{1}0 \rangle \{110\}$  slip systems were common to samples deformed at high temperature and those micro-indentated at room temperature. However, the slip systems of  $\langle 100 \rangle \{001\}$  were only observed in BaTiO<sub>3</sub> quenched from high temperatures [4]. Both types of the dislocations with  $\mathbf{b}_1 = \langle 100 \rangle$  and  $\langle 1\bar{1}0 \rangle$  have been determined in creep-deformed samples of the perovskite structure [4–10].

Grown-in dislocations with  $\mathbf{b} = \langle 100 \rangle$  have dissociated [7,11,12] into a series of half-loop partials in BaTiO<sub>3</sub> samples creep-deformed at 1400 °C in air. The half-loop partials resembling the scallop shape [7,11,12] were a characteristic feature to deformed microstructure. Nevertheless, observations by Doukhan and Doukhan [7] were confined to single crystals subjected to creep deformation at 1150–1570 °C before slowly cooled to room temperature. Studies on quenched BaTiO<sub>3</sub> samples from CO<sub>2</sub>-laser-sintering [13] have confirmed [11,12] that the  $\mathbf{b} = [001]$  dislocations

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dissociated into half-loop partials [12] as well as two collinear partials [11]. The dissociation into collinear partials has occurred by a mixed mechanism of glide and climb either on  $(1\ 1\ 1)$  [11] or  $(0\ 1\ \bar{1})$  [12] by Lin and Lu in samples sintered in air using CO<sub>2</sub>-laser [13], where rapid quenching to room temperature was possible.

Dissociation of dislocations with Burgers vector  $\mathbf{b}_1$  by the reaction of the type:  $\mathbf{b}_1 \rightarrow \mathbf{b}_2 + \mathbf{b}_3$ ,

$$[0\ 1\ 0] \rightarrow \frac{1}{2}[0\ 1\ \bar{1}] + \frac{1}{2}[0\ 1\ 1] \quad (1)$$

has resulted in two partial dislocations with orthogonal  $\mathbf{b}_2$  and  $\mathbf{b}_3$ . The half-loop partial  $\mathbf{b}_3 = 1/2[0\ 1\ 1]$  nucleated at high temperature was dissociated subsequently by climb in  $(0\ 1\ 0)$  while the other partial segment  $\mathbf{b}_2 = 1/2[0\ 1\ \bar{1}]$  remained stationary [7]. Another segment of the initial dislocation, with Burgers vector  $\mathbf{b}_1 = [0\ 1\ 0]$  normal to the half-loop lying in  $(0\ 1\ 0)$ , was not dissociated. However, the microstructure feature is not common in the perovskites taken as model materials, no such half-loop dislocations were detected in KTaO<sub>3</sub> [4] or CaGeO<sub>3</sub> [10] deformed by high-temperature creep.

Fig. 1 illustrates schematically the dissociation reaction of  $\mathbf{b} = [0\ 1\ 0]$  by climb in the  $(0\ 1\ 0)$  plane [7].

Both types of dislocations, i.e.  $\mathbf{b} = \langle 1\ 0\ 0 \rangle$  and  $\langle 1\ \bar{1}\ 0 \rangle$ , have dissociated into partials by the following reaction, respectively, in CaGeO<sub>3</sub>.

$$[1\ \bar{1}\ 0] \rightarrow \frac{1}{2}[1\ \bar{1}\ 0] + \frac{1}{2}[1\ \bar{1}\ 0] \quad (2)$$

$$[0\ 0\ 1] \rightarrow \frac{1}{2}[0\ 0\ 1] + \frac{1}{2}[0\ 0\ 1] \quad (3)$$

The latter (Eq. (3)) found [11] in CO<sub>2</sub>-laser-sintered BaTiO<sub>3</sub> has not been reported [4–10] for any other creep-deformed perovskite samples. The dissociated dislocations with  $\mathbf{b} = \langle 1\ 0\ 0 \rangle$  found in CaGeO<sub>3</sub> perovskite were in a pure climb configuration [10].

Investigating the microstructure of pressureless-sintered SrTiO<sub>3</sub> ceramics, only  $\mathbf{b} = \langle 1\ \bar{1}\ 0 \rangle$  was reported [9]. It was revealed by weak-beam imaging that  $\mathbf{b}_1 = [0\ \bar{1}\ 1]$  dissociated by pure climb and pure glide via the reaction:

$$[0\ \bar{1}\ 1] \rightarrow \frac{1}{2}[0\ \bar{1}\ 1] + \frac{1}{2}[0\ \bar{1}\ 1] \quad (4)$$

However, dissociation by the following reaction:

$$[0\ \bar{1}\ 1] \rightarrow [0\ \bar{1}\ 0] + [0\ 0\ 1] \quad (5)$$

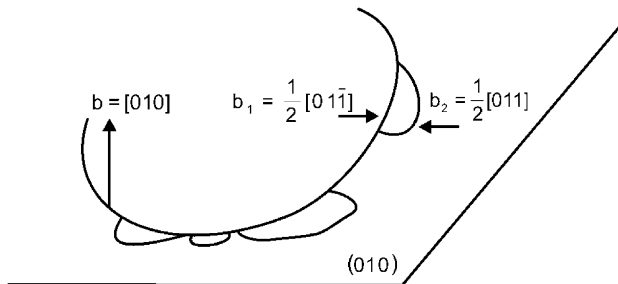


Fig. 1. A schematic illustration of dislocation dissociation by  $\mathbf{b}_1 = \mathbf{b}_2 + \mathbf{b}_3$  (redrawn from Ref. [7]).

as suggested by Poirier et al. [4], was not found in sintered SrTiO<sub>3</sub> ceramics.

In this study, the microstructure of pressureless-sintered (i.e. sintered in air), undoped and Sr-doped BaTiO<sub>3</sub> compositions has been analysed via transmission electron microscopy (TEM). Observations suggest that the glide systems of  $\langle 1\ \bar{1}\ 0 \rangle \{1\ 1\ 0\}$ ,  $\langle 1\ 0\ 0 \rangle \{1\ 1\ 0\}$  and  $\langle 1\ 0\ 0 \rangle \{0\ 0\ 1\}$  [4–12] have been activated when BaTiO<sub>3</sub> was sintered at 1400 °C in air. Dislocations dissociated into the scallop-shaped, half-loop partials, and collinear partials by Eqs. (4) and (5), respectively, has occurred. The dissociation reaction by Eq. (5), which has not been unequivocal in the past [7,9], is confirmed.

## 2. Experimental procedure

Commercially available BaTiO<sub>3</sub> powder (with (Ba/Ti)  $\approx 0.997$ , Ticon® HPB, Ferro, Niagara Falls, NY, USA) and SrTiO<sub>3</sub> powder (with (Sr/Ti)  $\approx 0.999$ , HPST-1, Fuji Titanium, Kanagawa, Japan) were used for the present study. Both powders containing TiO<sub>2</sub> excess are non-stoichiometric. Powders of appropriate quantities, doped and undoped with SrTiO<sub>3</sub>, were mixed in isopropyl alcohol (IPA) using Y<sub>2</sub>O<sub>3</sub>–ZrO<sub>2</sub> balls in a plastic bottle for 2 h. The mixed slurry was then dried at 120 °C for 12 h before deagglomerated using an agate mortar and pestle. The dried powder passed through  $\sim 75\ \mu\text{m}$  sieve to exclude large agglomerates was dry-pressed at 100 MPa in a WC-inserted steel die to pellets of  $\sim 5\ \text{mm}$  in diameter. They were debindered at 700 °C for 6 h before sintered in a conventional tube furnace at 1400 °C in air, followed by furnace-cooling to room temperature.

Sintered samples were sliced with a diamond-embedded saw blade, mechanically ground using SiC grits and polished successively to  $1\ \mu\text{m}$  roughness with diamond pastes. Polished sections were either thermally etched at 1200 °C for 30 min or chemically etched with 1% HF solution in order to delineate grain boundaries and the ferroelectric domains. Observations via scanning electron microscopy (SEM) using JEM6400 (JEOL, Tokyo, Japan) were made on Au–Pd-coated specimens. Thin foils were prepared by ultrasonic cutting of the sliced discs to 3 mm in diameter, mechanical polishing to  $<200\ \mu\text{m}$  thick and dimple-grinding (SBT-515, Southbay Technologies, San Clemente, CA, USA) to  $<20\ \mu\text{m}$  thick in the centre region before ion-beam thinning (Gatan 600 Duomill™) to electron transparency. They were analysed via TEM using JEOL AEM 3010 microscopes operating at 300 kV.

## 3. Results

### 3.1. Crystalline phases

Sintered undoped samples contained predominantly tetragonal (t-)BaTiO<sub>3</sub> with a minor amount of the monoclinic

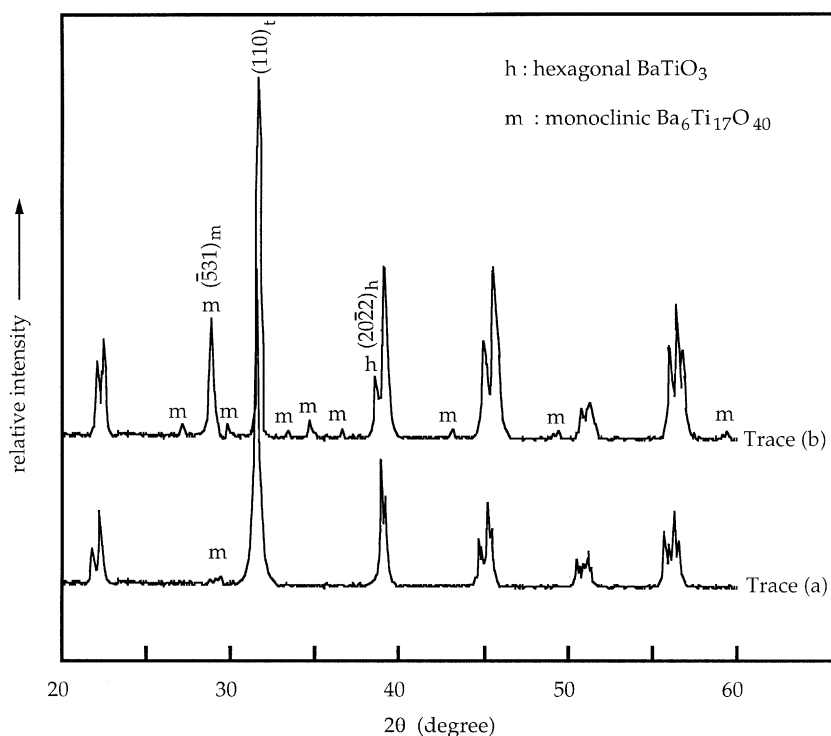


Fig. 2. XRD traces of (a) undoped and (b) SrO-doped BaTiO<sub>3</sub> samples sintered at 1400 °C.

(m-)Ba<sub>6</sub>Ti<sub>17</sub>O<sub>40</sub> (B<sub>6</sub>T<sub>17</sub>) second phase crystallised from the eutectic liquid formed at above 1332 °C [14]. This is shown in trace (a) of Fig. 2. The presence of B<sub>6</sub>T<sub>17</sub> is manifested in  $(\bar{5}31)_m$ , since the strongest  $(\bar{1}33)_m$  reflection has overlapped with  $(110)_t$  of BaTiO<sub>3</sub>. Its existence is clearly detected from the Sr-doped samples (trace (b)). The metastable retention of hexagonal (h-)BaTiO<sub>3</sub> [15] has

also occurred in the Sr-doped samples (as revealed by trace (b)). It can be unambiguously discerned from the hexagonal  $(20\bar{2}2)_h$  reflection. This peak has probably included  $(0006)_h$  appearing in its proximity. Other reflections from the hexagonal phase, although of higher intensities, have merged with those of the tetragonal phase and become indistinguishable from the XRD trace. Doping with SrTiO<sub>3</sub>

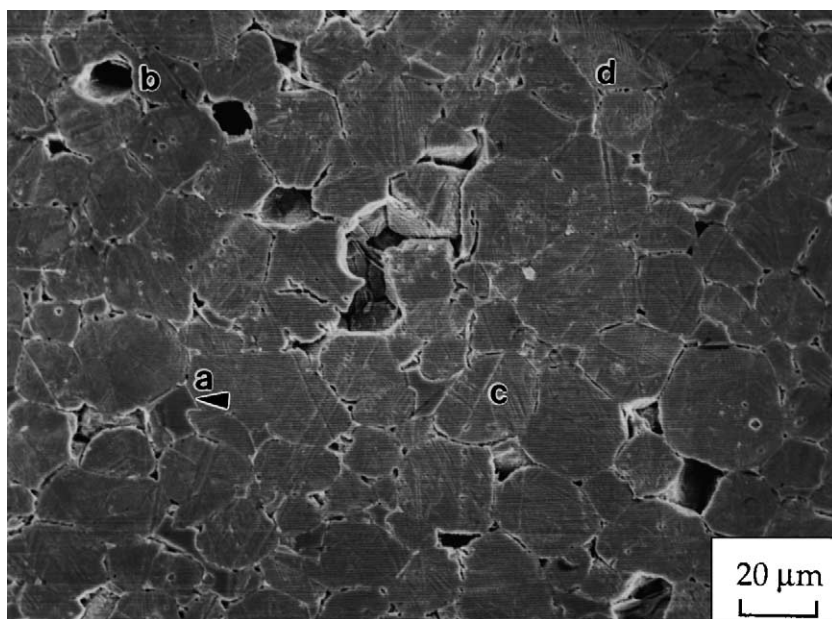


Fig. 3. Polished section of the Sr-doped BaTiO<sub>3</sub> ceramics showing the microstructural features of (a) second phase, (b) residual pores, (c) twinning and (d) ferroelectric domains (SEM-SEI).

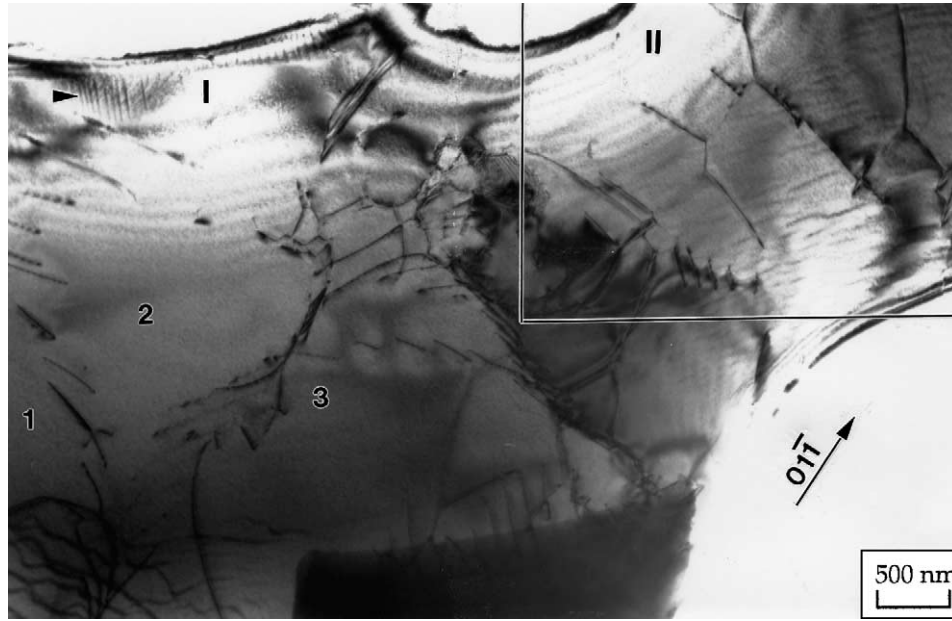


Fig. 4. A representative microstructure of the Sr-doped BaTiO<sub>3</sub> ceramics containing dislocations forming nodes, networks, tangles and low-angle grain boundaries (TEM-BF image).

has resulted in a systematic peak shift towards higher  $2\theta$  angle, e.g.  $(1\ 1\ 0)_t$  indicating a contracted unit cell.

Second phases at the triple-grain junctions containing B<sub>6</sub>T<sub>17</sub>, suggested by the XRD trace (b) in Fig. 2, were also confirmed by the energy-dispersive spectroscopy (EDS) of X-ray equipped with SEM. The representative microstructure features in sintered samples are (a) second phase (of B<sub>6</sub>T<sub>17</sub>), (b) residual pores, (c)  $\{1\ 1\ 1\}$  twins and (d) ferroelectric domains as indicated in Fig. 3.

### 3.2. Dislocations

Most of the dislocations found in sintered BaTiO<sub>3</sub>, undoped as well as Sr-doped formed nodes, networks, tangles and low-angle grain boundaries (LAGBs). An example of (Ba<sub>0.9</sub>Sr<sub>0.1</sub>)TiO<sub>3</sub>, sintered at 1400 °C for 100 h, is shown in Fig. 4 where dislocations of the framed regions I and II have been further analysed for their Burgers vectors ( $\mathbf{b}$ ) and line directions ( $\mathbf{u}$ ).

Polygonisation has occurred as evidenced by the formation of sub-grains, notably of region I in Fig. 4. It is shown at a higher magnification in Fig. 5a where sub-grains of 1, 2 and 3, associated with dislocation arrays A, B, C and D, were in slightly different Bragg diffraction conditions. The LAGBs of sub-grains 1–2 and sub-grains 2–3 are  $\sim 0.05^\circ$  and  $\sim 0.42^\circ$ , respectively. The misorientation was estimated by measuring the amount of shift ( $\Delta$ ) off the exact Bragg diffraction condition of  $Z = [1\ 1\ 1]$  for the individual sub-grains. The zone centre has moved along  $[\bar{1}\ 0\ 1]$  by  $\Delta \approx 8\text{ mm}$ , as indicated in Fig. 5b, when shifting from sub-grains 2–3. The misorientation ( $\theta$ ) caused by dislocation arrays A and B can be calculated by adopting:  $\Delta \approx L\theta$ ,

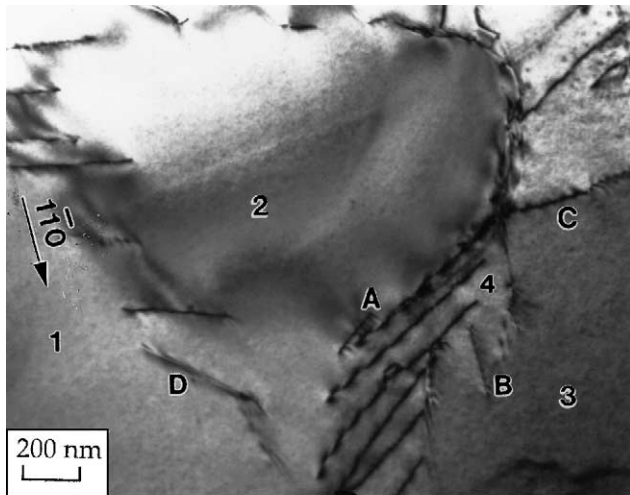
where  $L$  is the camera length. The formation of LAGBs requires [16] both climb and glide of edge dislocations during dynamic recovery.

The dislocations in arrays A, B and C (as indicated in Fig 5a), were determined for the line directions ( $\mathbf{u}$ ) and Burgers vectors ( $\mathbf{b}$ ) by the invisibility criterion of  $\mathbf{g} \cdot \mathbf{b} = 0$  and trace analysis. However, dislocation D was not determined for  $\mathbf{u}$  and  $\mathbf{b}$ . Results are listed in Table 1. Dislocations marked with A and B are the pure edge type, where  $\mathbf{u} \perp \mathbf{b}$  but they lie on different planes of  $(0\ 1\ 1)$  and  $(0\ 1\ 0)$ , which are then the respective glide plane for dislocations in arrays A and B. Dislocation C is of a mixed character with the angle  $\alpha$  of  $\mathbf{u} \angle \mathbf{b} = 45^\circ$  between dislocation line and Burgers vector. Further, its glide plane containing both  $\mathbf{b}$  and  $\mathbf{u}$  is likely to be  $(1\ 0\ 0)$ . The suggestion is that not only the  $\langle 100 \rangle \{001\}$  slip systems [4–12] have been activated by pressureless-sintering at 1400 °C, but also  $\langle 100 \rangle \{1\ 1\ 0\}$ . Further, the deformation of BaTiO<sub>3</sub> at high temperatures has been contributed by gliding of edge dislocations along  $\langle 100 \rangle$  on  $\{1\ 1\ 0\}$  as well as  $\{001\}$ . The present observation is consistent with those reported by both Doukhan and Doukhan [7] and Poirier et al. [4] for glide occurs similarly on the  $\{100\}$  and  $\{1\ 1\ 0\}$  planes [7], and dislocations

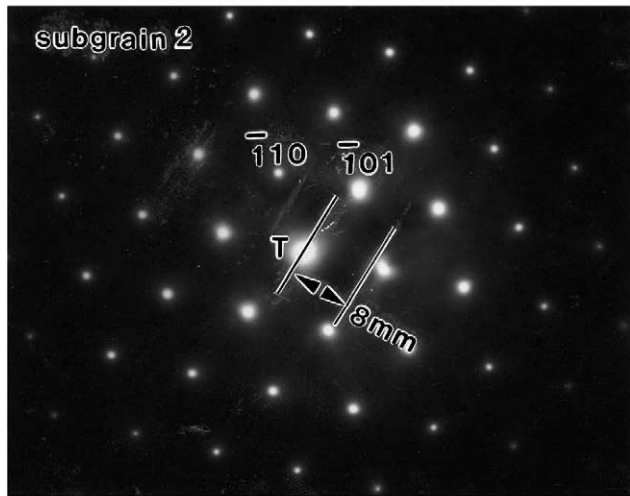
Table 1  
Analysis of the dislocation line vectors and Burgers vectors associated with sub-grains

Dislocation	A	B	C
$\mathbf{b}$	$[1\ 0\ 0]$	$[0\ 0\ 1]$	$[0\ 0\ 1]$
$\mathbf{u}$	$[0\ 1\ \bar{1}]$	$[1\ 0\ 0]$	$[0\ 1\ 1]$
Glide plane character	$[0\ 1\ 1]$	$[1\ 0\ 0]$	$[0\ 1\ 1]$
	Pure edge	Pure edge	$45^\circ$ mixed





(a)



(b)

Fig. 5. (a) Two-beam BF images of dislocation arrays A, B and C with (b) the corresponding SADPs (TEM).

with  $b=\langle 100 \rangle$  predominated [4] at high temperatures (of 1400 °C).

### 3.3. Nodes and networks

Region II of Fig. 4 at a higher magnification is given in Fig. 6a. Dislocations have met at a point and formed nodes whose Burgers vectors have been determined. In comparison, dislocation lines between the nodes of the dislocation network located in lower left corner (indicated with blank arrow in Fig. 6) have contracted [17] in much shorter lengths. The dislocations involved in forming the network of region II are those with the Burgers vectors of  $b=\langle 1\bar{1}0 \rangle$  as well as  $\langle 100 \rangle$ . It is illustrated schematically in Fig. 6b, where the dislocations lying in the same plane have reacted to form nodes and networks during sintering. The Burgers vectors of  $b_1 = [\bar{1}10]$ ,  $b_2 = [\bar{1}10]$  and  $b_3 = [010]$  are consistent with Frank's rule:  $b_1 = b_2 + b_3$ .

### 3.4. Dissociated dislocations

Fig. 7 presents the  $g\text{-}4g$  WBDF images of dislocations with  $b = \langle 010 \rangle$  and  $\langle 110 \rangle$ , respectively, in the Sr-doped samples sintered at 1400 °C for 100 h. No dislocation dissociations to collinear partials as those reported for SrTiO<sub>3</sub> [9] and BaTiO<sub>3</sub> [11] or the scallop-shaped half-partials as those also reported for BaTiO<sub>3</sub> [7,11,12] can be discerned in samples subjected to prolonged sintering at 1400 °C.

However, dislocations containing a series of small half-loop partials resembling scallops [7,11,12] have been observed in both undoped BaTiO<sub>3</sub> and Sr-doped BaTiO<sub>3</sub> sintered at 1400 °C for a shorter sintering of 10 h. The dissociated dislocations are consisted of three segments with Burgers vectors following the reaction:  $b_1 = b_2 + b_3$ , where  $b_2$  and  $b_3$  are the partial dislocations dissociated from the perfect dislocation  $b_1$ . The black dots, likely to be dislocation loops, and seen ubiquitously in samples sintered at >1400 °C [18] as indicated by empty arrows in Fig. 8b, have been analysed and reported in another manuscript.

The dissociation reaction [7] for dislocation 1, as labelled in Fig. 8a, may be described by

$$[001] \rightarrow \frac{1}{2}[101] + \frac{1}{2}[\bar{1}01] \quad (6)$$

where  $b_1 = [001]$  (the original dislocation),  $b_2 = 1/2[101]$  and  $b_3 = 1/2[\bar{1}01]$  (the scallop-shaped half-partials).

Dissociation by pure glide may have occurred in  $(010)$ , and by pure climb in  $(100)$  or  $(001)$  [4,8].

The dissociated segment,  $b'_1$ , of dislocation 2 (as labelled in Fig. 8a and referred to Fig. 8c) exhibits only residual contrast (as indicated by arrows). It also reveals that  $b_2$  of dislocation 1 (as indicated by arrows) containing a series of half-loops [7,11,12] is effectively invisible. Similarly, the segment of perfect dislocation  $b_1$  in dislocation 1 appears invisible as indicated by arrows in Fig. 8b. So does the  $b'_2$  segment of dislocation 2 in Fig. 8b. The seemingly dissociated  $b_1$  is a double image (as indicated by arrows) due to the two-beam condition was not strictly adhered, as is also evidenced by the whole dislocation line (Fig. 8b).

Dissociation reactions derived from the Burgers vectors determined for the two scallop-shaped half-partials labelled 1 and 2 in Fig. 8a and b have other possibilities. One for dislocation 1 as described earlier (Eq. (6)) and the other [7,9] for dislocation 2 is then

$$[101] \rightarrow [001] + [100] \quad (7)$$

where  $b'_1 = [101]$ ,  $b'_2 = [001]$  and  $b'_3 = [100]$ .

Dissociation by pure glide may also take place on  $(010)$  in which the Burgers vector  $b'_1 = [101]$  of the perfect dislocation and the two dissociated ones,  $b'_2$  and  $b'_3$ , lie. That is to say, dissociation of  $b'_1$  may have occurred in plane  $(010)$  containing the Burgers vectors of the three dislocations in

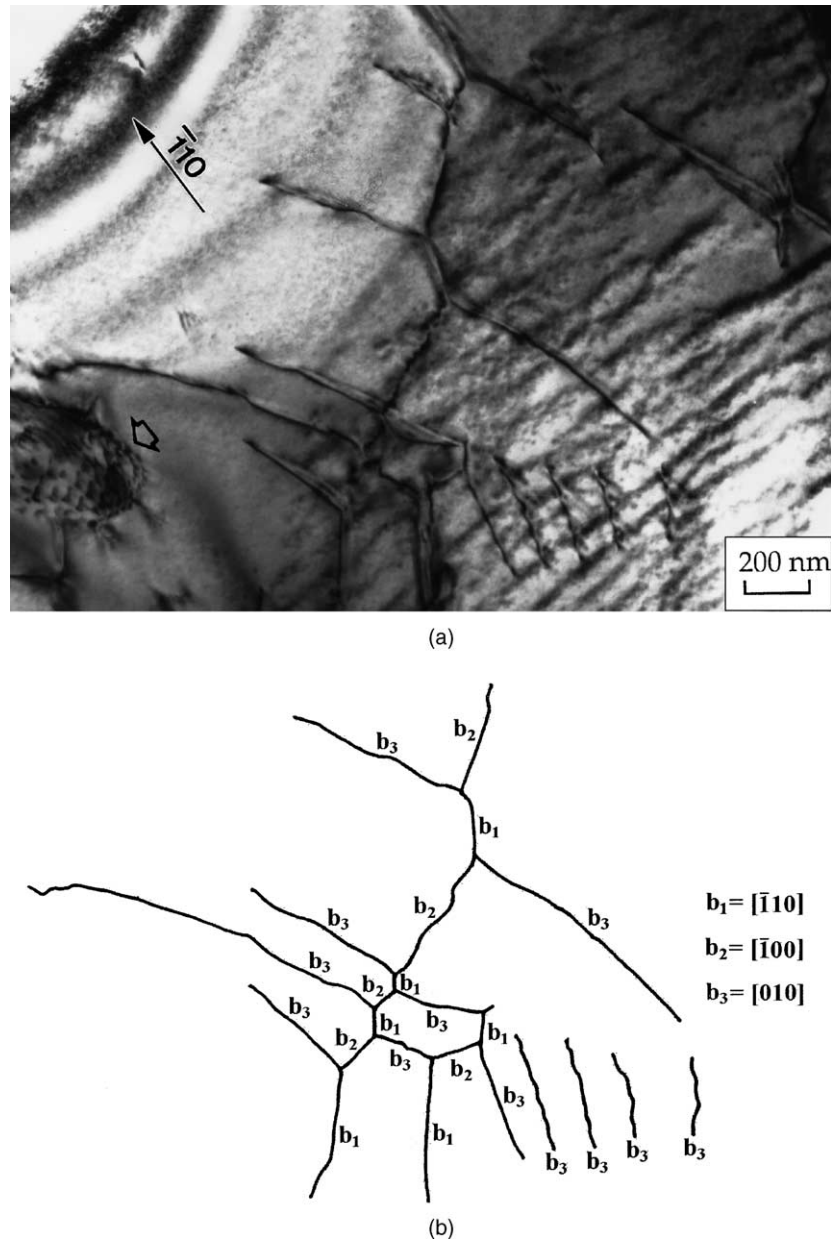


Fig. 6. Dislocations forming nodes and networks in (a) two-beam BF image (TEM) and (b) the schematic illustration correspondingly.

Eq. (7). Pure climb dissociation may take place in a plane whose normal is perpendicular to  $[0\ 1\ 0]$ , i.e. in the  $(1\ 0\ 0)$  or  $(0\ 0\ 1)$  plane. It has been suggested [4] that dissociation occurs in the perovskites [7,9] in planes other than the slip planes when dislocations move in a non-conservative fashion.

The scallop-shaped segments from the dissociated dislocations, shown in Fig. 8a and b, have two distinctive Burgers vectors of  $b_3 = 1/2[\bar{1}\ 0\ 1]$ , similar to previously reported [7,12], and  $b'_3 = [1\ 0\ 0]$ .

The dissociated dislocations 1 and 2 with the respective Burgers vectors are illustrated schematically in Fig. 8c.

## 4. Discussion

### 4.1. Dislocation dissociations

Plastic deformation by glide along  $\langle 1\ 1\ 0 \rangle$  and  $\langle 0\ 0\ 1 \rangle$  in  $\{1\ 1\ 0\}$  and  $\{0\ 0\ 1\}$  in  $\{1\ 0\ 0\}$ , as reported before for single-crystal [4,7] as well as polycrystalline  $\text{BaTiO}_3$  [12], and other perovskites [6], have also occurred in samples pressureless-sintered at  $1400^\circ\text{C}$  for 10 h.

The dissociation of dislocation 1 in Fig. 8a and b by Eq. (6) is identical to that reported by Doukhan and Doukhan [7]. Similarly, the suggestion is also that the half-loop partial of  $b_3 = 1/2[\bar{1}\ 0\ 1]$  has escaped from  $(0\ 0\ 1)$  with the other

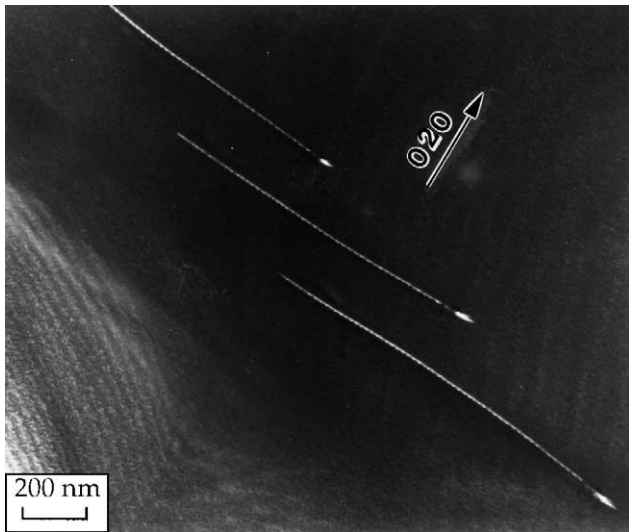


Fig. 7. Dislocations in Sr-doped BaTiO<sub>3</sub> samples sintered at 1400 °C for 100 h revealed no dissociations,  $b = \langle 1\ 1\ 0 \rangle$  ( $g=4g$  WBDF images, TEM).

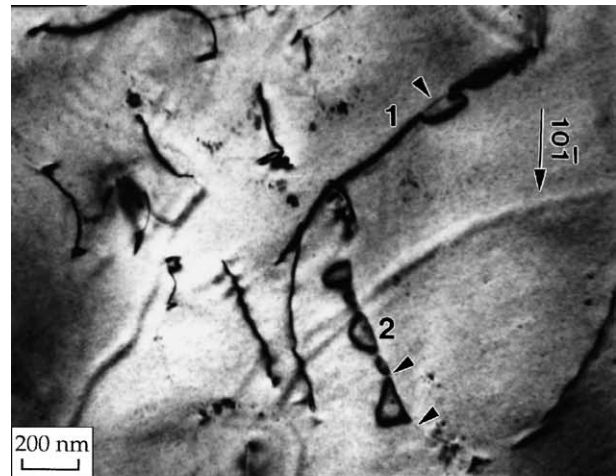
partial of  $b_2 = 1/2[1\ 0\ 1]$  still lying on it (as illustrated in Fig. 1).

Dissociation starting from cusps, which exhibited strong contrast under TEM, along the dislocation lines of  $b'_1 = [\bar{1}\ 0\ 1]$  was proposed [7], but without convincing experimental evidence. The “cusps”, if existed, further dissociated into similar scallop-shaped half-partials are unambiguously demonstrated by dislocation 2 in Fig. 8a and b. Dislocation 2 has followed the dissociation reaction as suggested [7] for dislocations with  $b = \langle 1\ \bar{1}\ 0 \rangle$  which contained cusps in deformed BaTiO<sub>3</sub> single crystals. The dissociation of  $b'_1$  into scallop-shaped half-partials occurred in the cusps of dislocations with  $b'_3 = [1\ 0\ 0]$  escaping [7] from the (1 0 0) or (0 0 1) plane. The dissociation reaction is described by Eq. (7). The dissociation plane of (1 0 0) or (0 0 1) may have been similar to those of dislocation 1 as was also reported by Doukhan et al. The dissociation (of Eq. (7)), however, would not lead to any significant reduction in the energy per unit length of dislocations.

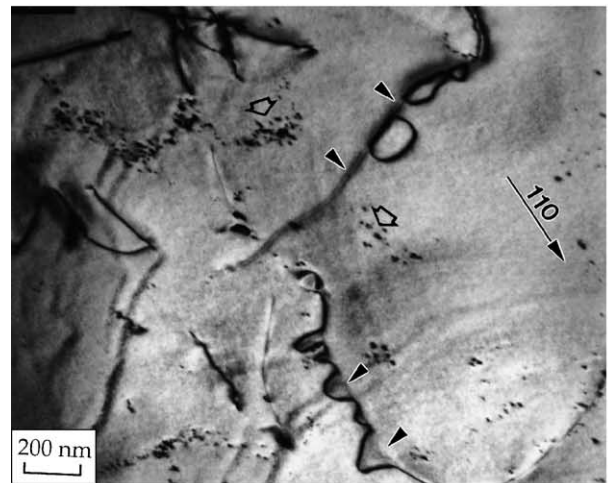
Because the line directions for all dislocations in Fig. 8a and b were not determined, whether their dissociation had taken place by climb [7,9], glide [9] or a mixed mechanism [11,12] cannot be confirmed at the present time.

#### 4.2. Recovered microstructure

The microstructure shown in Fig. 4 consisting of dislocation nodes, networks (region II) and sub-grains (region I) represents that the grains deformed by pressureless-sintering were undergoing dynamic recovery. Dislocation climb from the slip planes results in the formation of LAGBs, as shown in Fig. 5a, whereby the total strain energy is reduced. The long-range strain becomes localised in the proximity of dislocations. Sufficient local and long-range lattice diffusion via vacancies leading to dislocation climb has facilitated



(a)



(b)

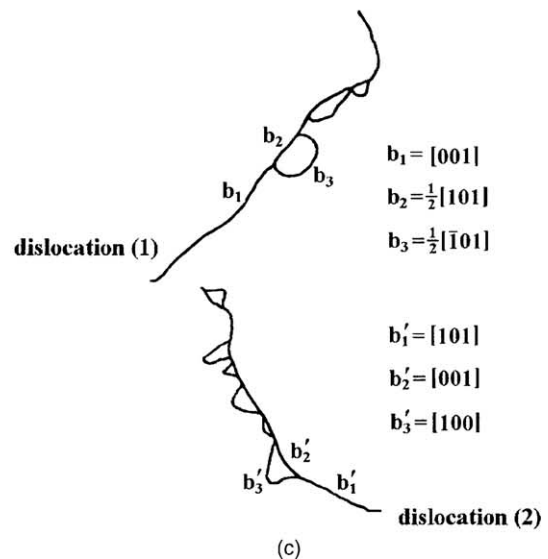


Fig. 8. Dislocations contain a series of small scallop-shaped half-loop partials from two-beam BF images of (a)  $g = 10$ , (b)  $g = 110$  (TEM) and (c) the schematic illustration for the dissociation reaction in dislocations 1 and 2.



the dynamic recovery at 1400 °C. Polygonisation forming sub-grains started upon the local rearrangement of dislocations, which have been generated by the intrinsic sintering stress ( $\Sigma$ ). The plastic deformation took place particularly in the initial stage of sintering [1] (as will be addressed below).

A sub-grain cell 4, apart from 1, 2 and 3, may also exist between the arrays of dislocations A and B as shown in Fig. 5a. The tilt boundary of  $\theta \approx 0.42^\circ$  determined for Fig. 5a and b has considered the dislocation arrays of A and B as a whole. Since  $b_A = [1\ 0\ 0]$  and  $b_B = [0\ 0\ 1]$  are both of the pure edge type (cf. Table 1), sub-grain boundaries separating 2–4 and 4–3 by dislocation arrays A and B, consisting of pure edge dislocation arrays, are the systematical tilt boundaries [18].

Both glide and climb must have occurred to facilitate sub-grain formation at 1400 °C [16,17]. Atom diffusion via lattice defects generated thermally in BaTiO<sub>3</sub> are likely to be the intrinsic Schottky type consisting of cation and anion vacancies,  $V''_{Ba}$ ,  $V'''_{Ti}$  and  $V_O^{\bullet\bullet}$  [19]. The fact that extensive dislocation climb has facilitated sub-grain formation during polygonisation (Figs. 4 and 5) supports the existence of a high concentration of thermal vacancies when BaTiO<sub>3</sub> was sintered at 1400 °C.

#### 4.3. Implications to densification mechanisms

Plastic flow was thought by Ogbuji et al. [1] to have contributed to densification in ceramic sintering, although others [20,21] concluded that its contribution was insignificant comparing to those by diffusion processes in pressureless-sintering. The sintering of ceramics may be conceived as high-temperature deformation driven by the thermodynamic driving force of  $\Delta p = \gamma_{sv}/\rho$ , where  $\gamma_{sv}$  is the surface-to-vapour surface energy and  $\rho$  is the neck curvature, which is originated from the net neck curvature ( $\sim 1/\rho$ ) [22]. Sintering can be differentiated from high-temperature creep since the effective stress (sometimes called the sintering stress ( $\Sigma$ )) translated from the chemical potential gradient ( $\Delta\mu$ ) into the form of a pressure difference ( $\Delta p$ , the thermodynamic driving force) is not a constant but strongly depends upon the sintered density (or, equivalently, residual porosity) [23,24]. The thermodynamic driving force is being consumed, and so reduced, continuously upon the sintering of the ceramic, densification as well as coarsening.

The slip systems of  $\langle 1\bar{1}0 \rangle \{110\}$ ,  $\langle 100 \rangle \{110\}$  and  $\langle 100 \rangle \{001\}$  in BaTiO<sub>3</sub> have been activated by the action of  $\Delta p$ , as evidenced from the microstructure observed. They are formed particularly in the initial stage when neck curvature is at its smallest. Dislocations are generated when  $\Delta p$  is at its largest, and distributed randomly on the slip planes of both  $\{001\}$  and  $\{110\}$ . Acting on the grain-boundary plane to push two grains closer together, the driving force then brings about overall system shrinkage via plastic deformation at high temperatures. The resultant effective stress intensified by neck curvature [1] must therefore exceed the critical resolved shear stress (CRSS) to have activated the

relevant slip systems in BaTiO<sub>3</sub>, as evidenced by the observations, but the exact values of CRSS not available in the literature will have to be determined by deforming single crystals as in sapphire [25].

Plastic deformation is important in the sintering of ceramics for it has contributed to the overall densification by activating the slip systems in BaTiO<sub>3</sub>. Nevertheless, even when densification, particularly in the initial stage, has occurred and been contributed by dislocation mechanisms, the overall sintering rate could still be determined by lattice diffusion in climb-controlled dislocation glide [26]. Indeed, pressureless-sintering kinetics of BaTiO<sub>3</sub> suggested [19] that the rate-determining mechanism for sintering is the lattice diffusion of Ba<sup>2+</sup> via vacancies.

## 5. Conclusions

Pressureless-sintering at 1400 °C has activated the slip systems of  $\langle 1\bar{1}0 \rangle \{110\}$ ,  $\langle 100 \rangle \{110\}$  and  $\langle 100 \rangle \{001\}$  in BaTiO<sub>3</sub>. The stresses resulting in the plastic deformation of BaTiO<sub>3</sub> are attributed to the thermodynamic driving force ( $\Delta p$ ) intensified by the neck curvature amongst powder particles, particularly in the initial stage of sintering when  $\Delta p$  is relatively large. Dislocations are dissociated by a climb mechanism into the scallop-shaped half-loop partials by either of the two reactions of:  $[1\ 0\ 1] \rightarrow [0\ 0\ 1] + [1\ 0\ 0]$  and  $[0\ 0\ 1] \rightarrow 1/2[1\ 0\ 1] + 1/2[\bar{1}\ 0\ 1]$ . Dynamic recovery takes place when polygonisation has begun at 1400 °C.

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